

Data collection in project HCT DUO

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REVERE

RESOURCE FOR VEHICLE
RESEARCH AT CHALMERS

REVERE vehicle lab

Chalmers University of Technology



REVERE – Resource for Vehicle Research

- Supporting academy, industry and public actors in advanced development, tests, validation and demonstrations
- Key areas:
 - Vehicle Automation
 - Active Safety
 - Vehicle Dynamics
 - Electromobility
 - Marine applications
 - Transport and logistics



CHALMERS



VOLVO
Volvo Car Corporation

REVERE research platforms

- Vehicles provided by Volvo Cars and Volvo Trucks serve as research platforms
- Interface for steering, braking, acceleration etc
- Sensors (Lidar, camera, radar, GPS, IMU etc depending on research requirements)
- Data logging equipment (on edge platform and cloud)
- Communication (over the air updates, data uploading, V2V, remote control etc)
- Open-source software platform OpenDLV used on all test vehicles



Selected REVERE research platforms



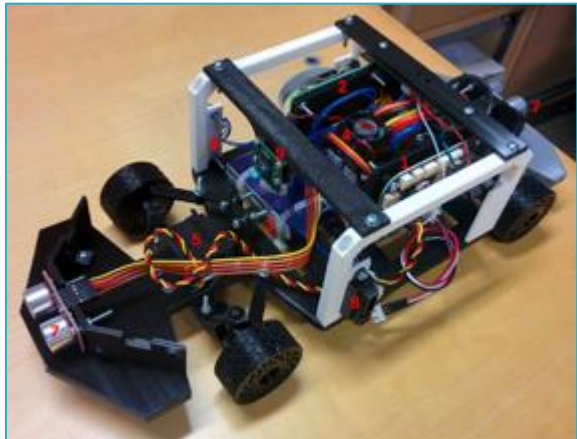
Volvo XC90 (two different)



Volvo FH16 (also trailers available)



Parator dolly with steerable axles



"Kiwi" 3D-printed miniature cars (50+ units)



Chalmers Formula Student Driverless

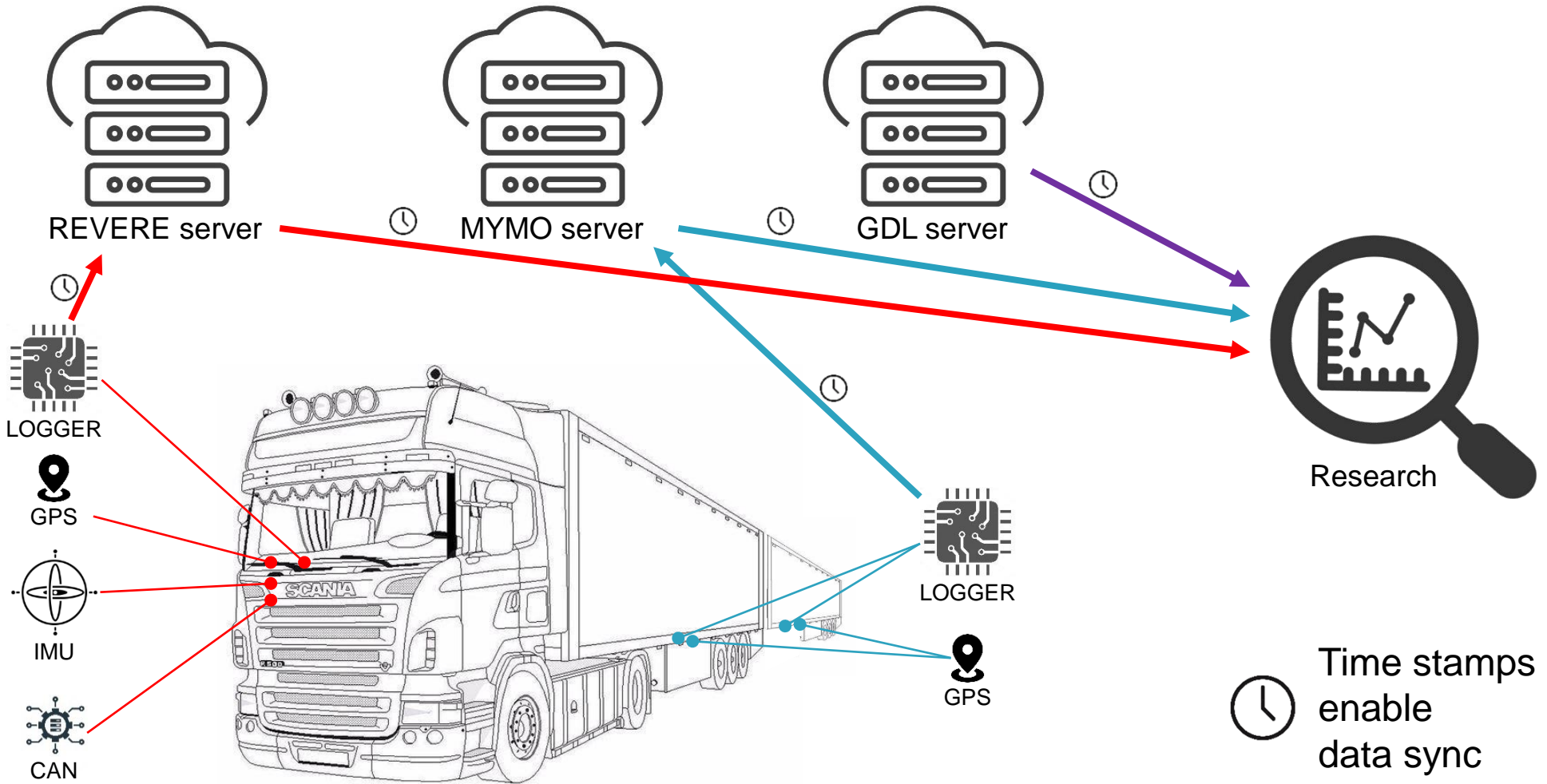


Pilot boat

HCT Duo Demo

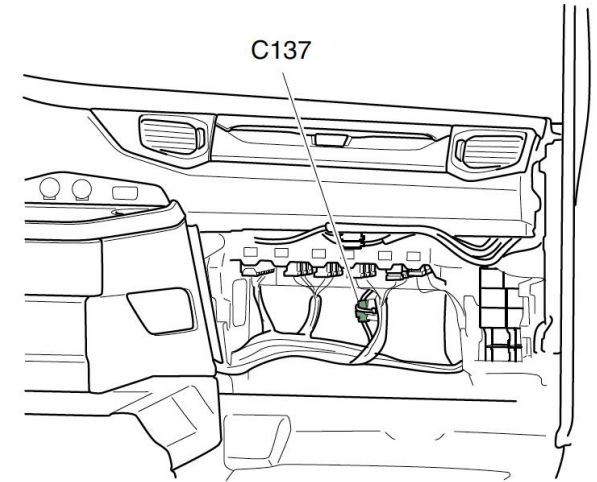


Data flow

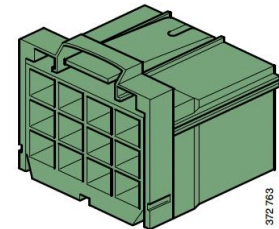


Data signals to be logged

- Position (GNSS/GPS)
- Accelerometer data
- CAN data from the truck (mainly fuel consumption)
- Data is time stamped using internal logger clock
- Data sampling rate 1Hz



Location of connector C137.



Connector C137.

Proposed data logger for the truck

- [Axotec Technologies RG—870M](#)
- Many different data input options
- Reads 2x CAN from the vehicle
- Gyroscope for vehicle inclination
- GNSS
- Data upload via 4G
- Simple installation in the vehicle
- Need for data filtering

